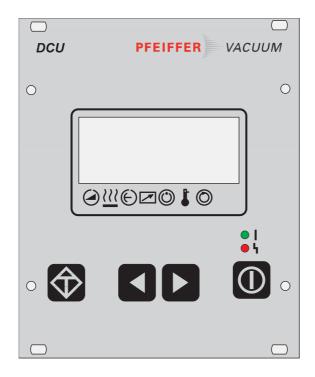
Pumping Operations With DCU



- Turbomolecular Pumps -



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Pictogram Definitions



Warning! Danger of an electric shock.



Warning! Danger of personal injury.



Caution! Danger of damage to the unit or system.



Please Note!

Attention to particularly important information on the product, handling the product, or to a particular part of the documentation.

Used Abbreviations

- DCU Operation and Display Unit
- TC Electronic Drive Unit
- TCK Electronic Drive Unit (Print Modul)

Please note

Current operating instructions are also available via *www.pfeiffer-vacuum.net* under "infoservice".

1. Introduction To These Instructions

The Display Control Unit DCU is a universal operating unit for the control and monitoring of PFEIFFER vacuum pumps.

These operating instructions describe the operations in respect of PFEIFFER VACUUM turbomolecular pumps. This manual is a component of the complete operating manual for your modular turbopump system. Depending on the configuration of your system, other operating instructions are included in your delivery consignment (please see the table). We make every effort to ensure that you are in possession of all the necessary product information but should anything be missing please get in touch with your local PFEIFFER VACUUM representatives or telephone the hotline number which you will find on the back cover of these operating instructions.

The respective documents are also available in PDF file format via the homepage www.pfeiffer-vacuum.de.

The following operating instructions are available for the TC pump program:

Product	Definition	Operating Manual Number
Turbomolecular Drag Pump	Definition of the turbopump	dependent on the type of pump*
Pumping operations with the DCU, turbopumps	Operating definitions /parameters	PM 800 547 BE
DCU 001, 100-600	Description of the control unit/installation	PM 800 477 BE
TPS 100, 200, 300, 600	Description of the power pack	PM 800 521 BE
Casing heating, turbopump	Description of the casing heating	PM 800 542 BE
Air cooling, turbopump	Description of the air cooling system	PM 800 543 BE
Water cooling, turbopump	Description of the water cooling system	PM 800 546 BE
Backing Pump relay box	Description of the backing pump control	PM 800 544 BE
Temperature Management System TMS	Description of the TMS installation	PT 0099 BE
Pfeiffer protocol RS 232/RS 485	Description of the serial interface protocol	PM 800 488 BE
Level Converter RS 232/RS 485	Description of the pumping control via the RS 232	PM 800 549 BE
TVF 005	Description of the venting valve	PM 800 507 BE
TIC 250	Description of the Profibus	PM 800 599 BE
PWM-Box	Description of the pulse width modulation	PM 800 563 BE
TCS 010	Description of the Pumping Station Control Unit	PT 0045 BE
Cover IP 54 for TC 600	Description of the water protection cover	PT 0024 BE
TBC 600	Description of the brake unit	PT 0018 BE
* The number is available from PFEIFFER VACUUM Service	or from the internet address shown in this manual.	

2. Parameter

2.1. General

All function relevant elements of the display control unit or pump are available in the DCU in the form of parameters. Each parameter has a parameter number and a clear text designation, for example **[P:026]** «OpMode TMP». The value of the parameter is always readable and in some instances can be altered. In principle there are three different types of parameter:

Parameter Typ	Function
Setting command	Activating/deactivating a parameter
Status request	Parameter status reques (readable only)
Set value standard	Altering a parameter

To adapt these parameters to the individual requirements of the user, the DCU provides two different parameter sets which are distinguished by the number of parameters involved. The respective parameter set is selected via **[P:794]** «Param. set». The parametering is always active.

Parameter Set	Comment	Setting [P:794] «Param. set»
Basic parameter set	Only parameters sorted according	0
	to number and parameter type	
Extended parameter set	Complete parameter set, sorted according to number and parameter type	1

Parameters which do not appear in the display can nevertheless be operated via the serial interface.

TC 600/750 Data Setting Commands (readable and writable) fact. setting| RS 485¹⁾ | Name, Description | Display min max 001 Heating Pre-selection, heating.ON/OFF OFF ON OFF R/W 0 002 Standby Standby ON/OFF OFF ON OFF R/W 0 L. 004 RUTime ctr Run-up time monitoring, ON/OFF OFF ON ON R/W 0 H Error acknowledgement W 009 Error ackn 0 Pumping station ON/OFF OFF 0N ON(* R/W 010 Pump stat ī 0 Venting enable ON/OFF ON ON(*) R/W 012 Vent enab OFF 0 Pre selection brake ON/OFF OFF ON OFF R/W 013 Brake enab 0 H 0N(* R/W Motor TMF Motor Turbopump ON/OFF OFF 0N 0 Configuration output K1; 0=switchpoint attained; 1= TMS regulator; 2=var. switchp. 024 Conf. Out1 0 2 0 R/W 7 OpMode BkP R/W 025 Operations mode backing pump, 0=non-stop; 1=intermittent; 2=switch on delayed 0 2 0 7 OpMode TMF Operations mode TMP 0=final rot. speed op.; 1=rot. speed setting m 0 (*) R/W 026 0 1 7 027 Gas mode 🖬 🛛 Gas mode 🛛 O=heavy inert gases; 1=other gases 0 1 0 R/W 7 028 Opmode rem Remote operations mode 0=standard, 1=Remote priority, 2 Remote error acknowl 0 2 0 R/W 7 Drive unit operations mode OFF=max., ON=reduced power intake OFF 0N OFF 029 OpMode Drv R/W 0 030 Vent mode Venting mode 0=controlled venting ; 1=no venting; 2=venting "On 0 0 R/W 7 032 Conf Out4 Configuration heating output; 0=Heat/TMS operations; 1=sealing gas valve control 0 0 R/W 1 7 035 Conf I/01 Configuration accessories ON/Output 1 (see chapter 3.21) 0 3 0 R/W 7 036 Conf I/02 Configuration accessories ON/Output 2 (see chapter 3.21) 0 3 1 R/W 7 055 Conf A01 🖬 | Configuration Analog Output 1 0=Rot Speed; 1=Power; 2=Current 0 2 ٥ R/W 7 Status request (only readable) Type² Display Name, Description fact. setting RS 485 ١Ŭ min max # Unit remote controlled, not choosable by 0 300 1 R Oil defic R 301 Oil deficiency turbopump 0 0 Rotation switch point attained R 302 0 Actual error code "no Err", "Errxxx" or "Wrnxxx" Error code 303 R 4 Over temperature Electronic drive unit 304 l Ì R 0 Ì 305 Over temperature turbopump R 0 0 306 Set rotation speed attained R 0 ۲ Turbopump accelerates R 307 0 308 Set rotspd Set rotation speed TMP 0 2000 R 1 in Hz Actual rotation speed TMP 0 R 309 Act rotspd in Hz 2000 1 TMP I-Mot Motor current TMP in A 0 R 310 15.0 2 Operating hours TMP in h (pump preset time) TMP Op hrs 0 99999 R 311 1 Drv Softw Software version electronic drive unit R 4 313 TMP DClink Motor voltage TMP in V 0 200.0 R 2 R Drv Op hrs Operating hours electronic drive unit 0 99999 314 1 TMP finspd Final rotation speed TMP in Hz 0 2000 R 315 1 Motor power TMP in W TMP power 0 1000 R 1 H 0 99999 R 319 Cvcl count Cycle counter 1 331 TMS ActTmp Heating TMS, actual value in °C 5 200 R 1 TMS regulator engaged ON/OFF OFF 333 TMS steady ON R 0 334 TMS maxTmp Maximum TMS temperature occured in °C 5 200 R 1 335 Heat type Heating type 0=conventional heating, 1=TMS 0 R 7 1E-10 1E3 340 Pressure Actual pressure value in mbar R 3 349 Drv Name Unit type electronic drive unit R 4 Unit type operating and display unit 3) 350 Ctr Name R 4 Software version Display and Control Unit DCU 3) 351 Ctr Softw R 4 360 Past Err1 Error storage, Position 1 (last error occuring) R 4 361 Past Err2 Error storage, Position 2 R 4 362 Past Err3 📃 🛛 Error storage, Position 3 R 4 363 Past Err4 🖬 🛛 Error storage, Position 4 R 4 Past Err5 Error storage, Position 5 R 4 364 Past Err6 🖫 | Error storage, Position 6 R 4 365 Past Err7 Error storage, Position 7 R 4 366 L. 367 Past Err8 Error storage, Position 8 R 4 Past Err9 Error storage, Position 9 R 4 368 R 4 369 Past Err10 🖬 🛛 Error storage, Position 10 Set values (readable and writable) ype²) fact. setting| RS 485 | Display Name, Description min max 12 700 TMP RUTime R/W maximum run-up time in mins 1 120 154) / 85 1 701 Switch pnt Rotation speed switchpoint in % 50 97 80 R/W H 1 TMSheatset TMS heating temperature set value in °C 704 30 90 40 R/W 1 707 TMProt set Rotation speed set value in rotation speed setting operations in % 20.0 100.0 50.0(*) R/W 2 708 DrvPwr set Drive power set in % 10 100 80 R/W 7 BKP Poff 710 Pmin for backing-pump interval operations [W] 0 1000 0 R/W 1 711 BKP Pon Pmax for backing-pump interval operations [W] 0 1000 0 R/W 1 717 Stbyrotset Rotation speed set value at standby operations (%) 20 100 66 R/W 2 719 Switch pnt2 Rotation speed switchpoint2 in % 5 97 20 R/W 1 720 Vent frequ Venting frequency as a % of the final rotation speed of the TMP 40 98 50 R/W 7 721 Vent time Venting time in s 6 3600 3600 R/W 1 Vacuum pressure gauge type 3) 738 Gaugetype R/W 4

(*) Function can only be affected via remote plug (X16)

A number/parameter in bold type is a basic parameter set

 \blacksquare = Parameter setting is saved internal and activated after re-switching on

🖫 🛛 Unit address

insert service line

2.2. Parameter Overview. numerical. DCU

 $\stackrel{(1)}{\xrightarrow}$ R = Parameter readable via interface /W = parameter writeable via interface. $\stackrel{(2)}{\xrightarrow}$ See Interface instruction "Pfeiffer Protocol RS 232/485" / PM 800 488 BN

1

255

0

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795

R/W

R/W

R/W

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TC 100/TCK 100

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3) Parameter only for DCU

4) TC 600/750 5) TC 100/TCK 100

Parameter set 0 = basic parameter set; 1 = extended parameter set ³⁾

794

795

797

Param. set

Servicelin

Address

2.3. Parameter Overview, Operations Oriented, DCU

	Display	Name, Description	min	max	fact. set	RS 485	Sect.
lun-	up time and	rotation speed switchpoint					
04	RUTime ctr	Run-up time monitoring, 0=0FF; 1=0N	OFF	ON	I ON	•	3.4.
00	TMP RUTime	maximum run-up time in mins	1	120	15/8	•	3.4.
)1	Switch pnt	Rotation speed switchpoint in %	50	97	80	•	3.4.
9	Switch pnt2	Rotation speed switchpoint 2 in %	5	97	20		3.11.
<u> </u>	ownen pinz		5	57	20		0.11.
en	eral operating	j information					
5	TMP finspd	Final rotation speed TMP in Hz	0	2000	-	•	3.4.
0	TMP I-Mot	Motor current TMP in A	0	15.0	-	•	3.4.
3	TMP DClink	Motor voltage TMP in V	0	200.0	-	•	-
6	TMP power	Motor power TMP in W	0	1000	-	•	-
1	TMP Op hrs	Operating hours TMP in h	0	99999	-	•	3.1.
		nent turbopump					
2	Standby	Standby ON/OFF	OFF	ON	OFF(*)	•	3.5.
)	Pump stat	Pumping station ON/OFF	OFF	ON	-	•	3.4.
}*	Motor TMP	Motor Turbopump ON/OFF	OFF	ON	-	•	3.10.
ò	OpMode TMP	Operations mode TMP 0=final rot. speed oper., 1=rot. speed setting	0	1	0	•	3.11.
1	gas mode	Gas mode 0=heavy inert gases; 1=other gases	0	1	0	•	3.8.
)	OpMode Drv	Operating mode drive unit OFF=max., ON=reduced power consumption	OFF	ON	OFF	•	3.4.
;	Set rotspd	Set rotation speed TMP in Hz	0	2000	-	•	3.4.
)	Act rotspd	Actual rotation speed TMP in Hz	0	2000	-	•	3.1.
,	Stbyrotset	Rotation speed set value at standby operations (%)	20	100	66	•	1
7	TMProt set	Rotation speed set value in rotation speed setting operations in (%)	20.0	100.0	50.0(*)	•	3.11.
	,						
eat	ting/cooling t	urbopump					
	Heating	Pre-selection, heating. 0=0FF; 1=0N	0	1	0(*)	•	3.6.
2	Conf Out4	Configuration heating output; 0=Heat/TMS operations; 1=sealing gas valve control	0	1	0()	•	3.7.
<u>د</u> 1*	TMS ActTmp	Heating TMS, actual value in °C	5	200	-	•	3.8.
3*	TMS Actimp TMS steady	TMS regulator engaged ON/OFF	OFF	0N	-	•	3.8.
5 4*			5	200	-	•	-
	TMS maxTmp			-		_	_
5* *	Heat type	Heating typ 0=conventional heating, 1=TMS, 2=cooling	0	2	-	•	3.6., 3.8.
4*	TMSheatset	TMS heating temperature set value in °C	30	90	40	•	3.8.
		u					
		lling turbopump					
2	Vent enab	Venting enable ON/OFF	OFF	ON	ON	•	-
0	Vent mode	Venting mode 0=automatic venting ; 1=do not vent; 2=venting "On"	0	2	0(*)	•	3.15.
0	Vent frequ	Venting frequency as a % of the final rotation speed of the TMP	40	98	50	•	3.15.
1	Vent time	Venting time in s	6	3600	3600	•	3.15.
um	ping station of	controlling					
5	OpMode BkP	Operations mode backing pump, 0=non-stop; 1=intermittent; 2=switch on delayed	0	2	0	•	3.12.
5**	Conf I/01	Configuration Accessories ON/Output 1 (see chapter 3.21)	0	3	0	•	3.20.
6**	Conf I/02	Configuration Accessories ON/Output 2 (see chapter 3.21)	0	3	1	•	3.20.
)	Pressure	Actual pressure value in mbar	1E-10	1E3	-	•	3.11.
8	Gaugetype	Vacuum pressure gauge type			-	•	3.11.
0	BKP Poff	Pmin for backing-pump interval operations [W]	0	1000	0	•	
1	BKP Pon	Pmax for backing-pump interval operations [W]	0	1000	0	•	
· ·	Bid Foll						
the	ers						
3*	Brake enab	Preselection Brake ON/OFF	OFF	ON	OFF	•	1
3" 4*	Conf. Out1	Configuration output K1 0=switchpoint attained; 1= TMS regulator		1	0	•	3.8.
т							
	OpMode rem	Remote operations mode 0=standard, 1=Remote priority, 2 Remote error acknowl.	0	2	0	•	3.14.
}	Conf A01		0	2	0	•	3.19.
} 5	Conf A01	Configuration Analogue Output 1	-		-	•	-
} ; ;	Error code	Actual error code "no Err", "Errxxx" oder "Wrnxxx"					-
3 5 3 2	Error code Drv Softw	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit			-	•	
8 5 3 2 1	Error code Drv Softw Ctr Softw	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit Software version Display and Control Unit			-	•	-
3 5 3 2 1 4	Error code Drv Softw Ctr Softw Param. set	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit Software version Display and Control Unit Parameter set 0=basic parameter set; 1=extended parameter set	0	1	- 0	•	3.43.15
8 5 3 2 1 4 5	Error code Drv Softw Ctr Softw Param. set Servicelin	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit Software version Display and Control Unit Parameter set 0=basic parameter set; 1=extended parameter set insert serviceline	0		-	•	
3 5 2 1 4 5	Error code Drv Softw Ctr Softw Param. set	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit Software version Display and Control Unit Parameter set 0=basic parameter set; 1=extended parameter set		1 255	- 0	•	3.43.15
8 5 2 2 1 4 5 7	Error code Drv Softw Ctr Softw Param. set Servicelin Address	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit Software version Display and Control Unit Parameter set 0=basic parameter set; 1=extended parameter set insert serviceline	0		- 0 795	•	3.43.15 PM477E
3 5 2 2 1 4 5 7 7	Error code Drv Softw Ctr Softw Param. set Servicelin Address e of failures	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit Software version Display and Control Unit Parameter set 0=basic parameter set; 1=extended parameter set insert serviceline Unit address	0		- 0 795	•	3.43.15 PM477B
3 5 2 1 4 5 7 7 abl	Error code Drv Softw Ctr Softw Param. set Servicelin Address e of failures Past Err1	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit Software version Display and Control Unit Parameter set Debasic parameter set; 1=extended parameter set insert serviceline Unit address	0		- 0 795	•	3.43.15 PM477E - 4.3.
3 5 2 1 4 5 7 7 abl	Error code Drv Softw Ctr Softw Param. set Servicelin Address e of failures	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit Software version Display and Control Unit Parameter set 0=basic parameter set; 1=extended parameter set insert serviceline Unit address	0		- 0 795	•	3.43.15 PM477E -
3 5 2 1 4 5 7 7 7 7 0	Error code Drv Softw Ctr Softw Param. set Servicelin Address e of failures Past Err1	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit Software version Display and Control Unit Parameter set Debasic parameter set; 1=extended parameter set insert serviceline Unit address	0			• • • • • • • • •	3.43.15 PM477E - 4.3.
3 5 2 2 1 4 5 7 7 7 abl 2	Error code Drv Softw Ctr Softw Param. set Servicelin Address e of failures Past Err1 Past Err2	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit Software version Display and Control Unit Parameter set insert serviceline Unit address	0		0 795 1	• • • •	3.43.15 PM477E - 4.3. 4.3.
3 5 2 2 1 5 7 7 abl 2 2 3	Error code Drv Softw Ctr Softw Param. set Servicelin Address e of failures Past Err1 Past Err2 Past Err3 Past Err4	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit Software version Display and Control Unit Parameter set 0=basic parameter set; 1=extended parameter set insert serviceline Unit address Error storage, Position 1 (last error occuring) Error storage, Position 2 Error storage, Position 3 Error storage, Position 4	0			• • • •	3.43.15 PM477E - 4.3. 4.3. 4.3. 4.3.
3 5 2 2 1 4 5 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7	Error code Drv Softw Ctr Softw Param. set Servicelin Address e of failures Past Err1 Past Err2 Past Err3 Past Err4 Past Err5	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit Software version Display and Control Unit Parameter set 0=basic parameter set; 1=extended parameter set insert serviceline Unit address Error storage, Position 1 (last error occuring) Error storage, Position 2 Error storage, Position 3 Error storage, Position 4	0			• • • • •	3.43.15 PM477E - 4.3. 4.3. 4.3. 4.3. 4.3. 4.3.
3 5 3 2 1 4 5 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7	Error code Drv Softw Ctr Softw Param. set Servicelin Address e of failures Past Err1 Past Err2 Past Err3 Past Err3 Past Err5 Past Err6	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit Software version Display and Control Unit Parameter set 0=basic parameter set; 1=extended parameter set insert serviceline Unit address Error storage, Position 1 (last error occuring) Error storage, Position 2 Error storage, Position 3 Error storage, Position 4 Error storage, Position 5 Error storage, Position 6	0			• • • • • • • • • • • •	3.43.15 PM477E - 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3.
8 5 3 2 1 4 5 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7	Error code Drv Softw Ctr Softw Param. set Servicelin Address Past Err1 Past Err2 Past Err3 Past Err4 Past Err5 Past Err6 Past Err7	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit Software version Display and Control Unit Parameter set 0=basic parameter set; 1=extended parameter set insert serviceline Unit address Error storage, Position 1 (last error occuring) Error storage, Position 2 Error storage, Position 3 Error storage, Position 4 Error storage, Position 5 Error storage, Position 7	0			• • • • • • • • • • • • • • • • • • •	3.43.15 PM477E - 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3.
B 5 5 7 7 8 8 7 7 7 7 7	Error code Drv Softw Ctr Softw Param. set Servicelin Address e of failures Past Err1 Past Err2 Past Err3 Past Err6 Past Err6 Past Err7 Past Err7 Past Err7 Past Err7	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit Software version Display and Control Unit Parameter set 0=basic parameter set; 1=extended parameter set insert serviceline Unit address Error storage, Position 1 (last error occuring) Error storage, Position 2 Error storage, Position 4 Error storage, Position 5 Error storage, Position 7 Error storage, Position 7	0			• • • • • • • • • • • • • • • • • • • • • • • • • • • • • •	3.43.15 PM477E - 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.
8 5 3 2 1 4 5 7 abl 3 2 3 3 4 5 5 6 6 7 8	Error code Drv Softw Ctr Softw Param. set Servicelin Address Past Err1 Past Err2 Past Err3 Past Err4 Past Err5 Past Err7 Past Err7 Past Err7 Past Err7 Past Err7 Past Err7 Past Err7 Past Err7 Past Err7 Past Err7	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit Software version Display and Control Unit Parameter set 0=basic parameter set; 1=extended parameter set insert serviceline Unit address Error storage, Position 1 (last error occuring) Error storage, Position 3 Error storage, Position 5 Error storage, Position 6 Error storage, Position 7 Error storage, Position 8	0			• • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • •	3.43.15 PM477E - 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.
B 5 5 7 7 8 8 7 7 7 7 7	Error code Drv Softw Ctr Softw Param. set Servicelin Address e of failures Past Err1 Past Err2 Past Err3 Past Err6 Past Err6 Past Err7 Past Err7 Past Err7 Past Err7	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit Software version Display and Control Unit Parameter set 0=basic parameter set; 1=extended parameter set insert serviceline Unit address Error storage, Position 1 (last error occuring) Error storage, Position 2 Error storage, Position 4 Error storage, Position 5 Error storage, Position 7 Error storage, Position 7	0			• • • • • • • • • • • • • • • • • • • • • • • • • • • • • •	3.43.15 PM477E - 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.
3 5 5 7 abl 7 abl 7 abl 7 7 3 3 3 3 3 3	Error code Drv Softw Ctr Softw Param. set Servicelin Address Past Err1 Past Err2 Past Err3 Past Err4 Past Err5 Past Err6 Past Err7 Past Err7 Past Err7 Past Err7 Past Err7 Past Err9 Past Err10	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit Software version Display and Control Unit Parameter set 0=basic parameter set; 1=extended parameter set insert serviceline Unit address Error storage, Position 1 (last error occuring) Error storage, Position 3 Error storage, Position 5 Error storage, Position 6 Error storage, Position 7 Error storage, Position 8	0			• • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • •	3.43.15 PM477E 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4
bl	Error code Drv Softw Ctr Softw Param. set Servicelin Address e of failures Past Err1 Past Err2 Past Err3 Past Err4 Past Err5 Past Err7 Past Err7 Past Err7 Past Err7 Past Err7 Past Err9 Past Err9 Past Err10	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit Software version Display and Control Unit Parameter set 0=basic parameter set; 1=extended parameter set insert serviceline Unit address Error storage, Position 1 (last error occuring) Error storage, Position 2 Error storage, Position 3 Error storage, Position 4 Error storage, Position 5 Error storage, Position 6 Error storage, Position 7 Error storage, Position 8 Error storage, Position 10	0			• • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • •	3.43 PM47 - 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3.
bl	Error code Drv Softw Ctr Softw Param. set Servicelin Address Past Err1 Past Err2 Past Err3 Past Err6 Past Err6 Past Err7 Past	Actual error code "no Err", "Errxxx" oder "Wrnxxx" Software version electronic drive unit Software version Display and Control Unit Parameter set 0=basic parameter set; 1=extended parameter set insert serviceline Unit address Error storage, Position 1 (last error occuring) Error storage, Position 2 Error storage, Position 3 Error storage, Position 4 Error storage, Position 5 Error storage, Position 6 Error storage, Position 7 Error storage, Position 8 Error storage, Position 10	0			• • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • • •	3.43.1 PM477 - 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3. 4.3.

PFEIFFER VACUUM 5

3. Pumping Operations

3.1. General

On delivery the pre-set basic parameter sets contain the following parameters:

Setting Command [P:0xx]	Status Request [P:3xx] (readable only)	Set Value Standard [P:7xx]
001: Heating (ON/OFF)	308: Set rotation speed, TMP (in Hz)	700: maximale Anlaufzeit (in min)
002: Stand-by (ON/OFF)	309: Actual rotation speed TMP (in Hz)	701: Schaltpunkt (in %)
	310: TMP Motor current (in A)	794: Parametersatz
	311: operating hours, TMP (in h)	

On delivery, parameter **[P:794]** «Param. Set» has been preset to the value "0" (basic parameter set). By setting the value to "1" you access the extended parameter set.

3.2. Switching On The DCU

→ Make the connection to the Serial Interface RS 485.

DCU 001:

→ Switch on the external voltage supply to the TOC.

DCU 100/150/200/300/600:

Switch on the DCU with switch S1 on the rear panel.

Self Testing

After switching on, the DCU performs a self-test and also a test on the connected turbo electronics. During the test a bar appears in the display in line 4 and this shows the progress of this procedure.

Display test: All signs in the LC display are shown for a short time in black.

LEDs test: During the whole testing procedure the red and the green LEDs illuminate.

DCU self-test: The DCU hardware tests itself.

Testing the connection to the turbo electronics: The correct connection to the turbo electronics and their identity are checked.

Parameter test: Information regarding the parameters is loaded.

Identification of the connected components: The designation of the drive unit is displayed.

Providing there are no errors the DCU is now ready to operate.

3.3. Short Overview Operation



Selecting Parameters

→ Selecting parameters with push-button 🗳 (backwards)

or **D** (forwards). keeping the key depressed enables

rapid scrolling.

Setting Parameters

- Select Parameter.
- → Depress key-button and simultaneously till an arrow (--->) will appear in the second line from the top.
- -> Arrow disappears, if there is no setting after 8 sec..
- → With key-button reduce the value and with keybutton increase the value.
- → Depress key-button and simultaneously till the arrow (--->) disappears.
- -> The Parameter is set.

Error acknowledgement

→ Depress key-button 🍄 for a duration of min. 2 seconds.

For a more comprehensive description please refer to the operating instructions for the DCU / PM 800 477 BN.

3.4. Switching The Pumping Station ON/OFF

Please Note:

Before switching on the pumping station the set value **[P:7xx]** and setting commands **[P:0xx]** should be checked for their suitability with regard to the selected pump and pumping process.

- ➡ Remove the remote plug on the TC (only TC 600).
- ➡ Switch on switch S1 on the mains power unit.
- ➡ Select «794 : Param. Set» and set to «1».
- Check the relevant set value standards and setting commands (Section 2.2.).
- ➡ Select «023 : motor TMP» and set to «ON<u>» (only TC 600).</u>
- Switch on the pumping station with key O on the DCU or via the serial interface remote control or Parameter [P:010] «Pump stat» on the DCU.

Start-up of the turbopump

After successful completion of the self test, the turbopump starts up and the backing pump is driven. The rotation speed switchpoint **[P:701]** must be attained within the pre-set startup time **[P:700]**. Both parameters can be matched to the process. If an error code is displayed please refer to the error code table in section 4.

When the error is acknowledged the start-up time is reset.

Operations with mains voltages 90 - 132V



In case of this rated voltage the output power of the TPS (power supply) or DCU 600 (Control unit with power supply) is reduced.

Therefore the power input of the pump must be adapted with the DCU and via the parameters **[P:029]** and **[P:708]**.

- → Select «794 : Param. Set» and set to «1».
- → Select «029 : OpMode drv».
- ⇒ Set to «1» = reduced power take-up TC600.
- Select «708 : DrvPwr Set» and adjust to the relating pump type (see table below).

Pump type	Adjustment [P:708]
1001/1601/2201	80%
1201/1501/1801/2101/2301	60%
	I

If the TC is not set the error code **«E001**» or **«F007**» is displayed.

3.5. Switching Stand-By ON/OFF

- → Select «002 : Standby».
- → Select «OFF» oder «ON».

"Stand-by mode" is the operation of the pump at 66% of its final rotation speed (factory setting).This value is changeable.

→ Select «717 : Stbyrotset».

→ Adjust Standby rotation speed in the range of 20-100%.

Stand-by is recommended during operating breaks. The function can also be selected via the remote control or the serial interface.

During activ stand-by the rotation speed set point **[P:707]** refers always to the adjusted stand-by rotation speed **[P:717]**.

Stand-by mode is not possible in rotation speed setting mode (please see section 3.12).

At stand-by mode, pumps with integrated oil pump are first accelerated to 60% of their nominal rotation speed even if the set stand-by rotation speed is <60% x f_{nom} .

During this time the final rotation speed ist shown via **[P:308]** «set rotation speed». After reaching 60% of speed the adjusted stand-by rotation speed is displayed **[P:717]**.

3.6. Switching The Casing Heating ON/OFF

The TC 600 automatically recognizes a connected casing heating and sets according to the parameters **[P:355]** «Heat type» to «0». If no heating is connected «1» is displayed.

To control the casing heating on the TC 100/TCK 100 it is necessary to select the respective accessory input and output (see section 3.21.)

- → Select «794 : Param. Set» and set to «1».
- ➡ Select «335 : Heat type» and check setting to «0».
- → Select «001 : Heating».
- → Select «OFF» or «ON».

The casing heating is switched on and off dependent on the rotation speed switchpoint. Undershooting the rotation speed switchpoint causes the heating to be switched off. The status of the casing heating can be seen on the LC display on the DCU.

The function "casing heating" can be called up either via the serial interface or the remote control.

3.7. Sealing Gas Valve Control

Operation of the heating output "Heat/TMS" may be configured through **[P:032]**. At this output also a sealing gas valve may be driven by a venting valve.

- → Select «794 : Param. Set» and set to «1».
- → Select «032 : Conf Out4» and set to «1».

A valve connected to the connection "Heat/TMS" can be switched on at any time independently only through **[P:001]** or the corresponding control input "Heating ON" at the remote connector.

- ➡ Select «001 : Heating».
- ➡ Choose «OFF» or «ON».

3.8. Operations With Temperature Management System (TMS) (only TC 600/750)



The Temperature Management System (TMS) comprises a regulatable heating system which is installed in the fore-vacuum part of the turbomolecular pump. Heating up to a maximum of 90°C prevents the condensation of process gases or by-products in this part of the pump.

As a matter of principle, the TMS heating is only activated on attainment of the rotation speed switchpoint **[P:701]** The TC 600 automatically recognizes a connected TMS heating unit and sets the parameter **[P:335]** «Heat type» to «1».

Activating TMS mode

- → Select «794 : Param. Set» and set to «1».
- → Select «335 : Heat type» and check setting.
- ➡ Select «704 : TMSheatset».
- ➡ Enter set temperature value «30°C...90°C».
- ➡ Acknowledge the value.
- ➡ Select «001 : Heating» and set to «1».

With **[P:001]** «Heating» The TMS heating can be activated and deactivated at any time with «1» or «0» respectively.

In addition to the above parameters (which are used to start the TMS) other parameters are also available to support working with the TMS:

Calling up the TMS temperature

→ Select «331 : TMS ActTmp» and read off the temperature.

TMS set temperature attained?

➡ Select «333 : TMS steady» and read off the information.

Function of switch "output 1" (only TC 600)

The switch output 1 is normally set to "high" on the rotation speed switchpoint being exceeded. The function of switch output 1 can be re-programmed so that switch output 1 is "high" only when the TMS set temperature is attained.

→ Select «024 : Conf. Out1» and set to «1».

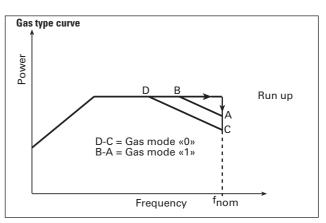
This information can be used, for example, as an input signal for a higher ordered process control.

3.9. Gas Type Dependent Operations

To protect the rotors against overheating, the maximum power on some turbopumps is limited to the nominal rotation speed. Normally, with a lower, pre-set rotation speed, more power can be provided. This frequency/power curve is dependent on the type of gas.

Selecting the gas type

- ➡ Select «794 : Param. Set» and set tof «1».
- → Select «027 : gas mode».
- ➡ Select «0» for heavy, noble gases and «1» for other gases.



The rotation speed is reduced when the gas dependent maximum power is exceeded until there is equilibrium between the permissible power and the gas friction. To avoid rotation speed fluctuations it is recommended to set (in rotation speed setting mode) the equilibrium frequency or a somewhat lower frequency.

3.10. Switching The Turbopump ON/OFF (only TC 600/750)

During pumping station operations (pumping station "ON") the turbopump can be switched on and off separately:

- ➡ Select «023 : Motor TMP».
- → Select «OFF», or «ON» as required.

3.11. Adjusting Rotation Speed Switchpoint

The speed switch point may be used to generate the message "Pump ready". As soon as the speed exceeds, respectively drops below the speed switch point 1 **[P:701]** «Switch pnt» the switched output is energized or de-energized. The factory default setting is 80%.

Simple Switch Point Adjustment (upper value only)

- ➡ Select «701 : Switch pnt».
- Adjust the switch point in the range between 50-97%.
- Confirm the adjustment.

Depending on the setting of the parameter **[P:024]** «Conf Out1» the lower and the upper speed switch point may be influenced simultaneously.

The factory default setting is 20, respectively 80% of the final rotation speed.

Double switch point adjustment (lower and upper value)

With this function different switch points at start up or shut down can be set and evaluated.

- → Select «024 : Conf Out1».
- ➡ Set the parameter to «2».
- ➡ Confirm the adjustment.

The speed switch point can now be varied through two further parameters:

Activated drive

In the case of an activated drive (**[P:010]** and **[P:023]** set to "**ON**") the switch point output is driven independently of the setting for the switch point 1 **[P:701]**. As soon as the speed exceeds the adjusted switch point, the switch point output is energized. The setting may be selected between 50 and 97% of the final rotation speed.

- ➡ Select «701 : Switch pnt».
- → Adjust the switch point in the range between 50-97%.
- ➡ Confirm the adjustment.

Deactivated drive

In the case of a deactivated drive (**[P:010]** and **[P: 023]** set to "**OFF**") the switch point output is driven independently of the setting for the switch point 2 **[P:719]**. As soon as the speed drops below the adjusted switch point, the switch output is de-energized. The setting may be selected between 5 and 97% of full speed.

- → Select «719 : Switch pnt2».
- → Adjust the switch point in the range between 5-97%.
- Confirm the adjustment.

3.12. Rotation Speed Setting Mode

The rotation speed setting mode is selected if the turbopump volume flow rate should be reduced. The pressure ratio of the pump reduces exponentially with the rotation speed.

Rotation speed standard in rotation speed setting mode

- ➡ Select «794 : Param set» and set to «1».
- ➡ Select «707 : TMProt set».
- ➡ Select the rotation speed in the range from 20%.....100%.

Operating mode, turbopump

→ Call up «026 : OpMode TMP».

→ Select "1" for rotation speed setting mode.



The stand-by mode is ineffective in rotation speed setting mode. The rotation speed switchpoint has been fixed at 20%. The rotation speed setting mode can be set via the remote control or the serial interface.

Pumps with integrated oil pumps are first accelerated, in rotation speed setting mode, to 60% of their rated rotation speed, also where the set rotation speed is <60% xf_{nom}.

During this time the final rotation speed ist shown via **[P:308]** «set rotation speed». After reaching 60% of speed the adjusted stand-by rotation speed is displayed **[P:717]**.

3.13. Pressure Measurement

With the use of a high vacuum pressure gauge the pressure in the vacuum chamber is shown in the DCU display.



Basically an exactly pressure measurement is not possible by the DCU. This is especially indicated at linear working gauges in the lower pressure range. In case of doubt an intended measuring unit should be used.

The following pressure gauges are automatically recognized by the DCU:

Pressure Gauge	P_{min} [mbar]	P_{max [} mbar]
TPR 2xx	5E-4	1E+3
PKR 2xx	5E-9	1E+3
ACR 261/CMR 261/APR 250/260	1E-1	1E+3
ACR 262/CMR 262	1E-2	1E+2
ACR 263/CMR 263	1E-3	1E+1
CMR 264	1E-4	1E0

Requesting the type of pressure gauge

- ➡ Select «794 : Param set» and set to «1».
- → Select «738 : gauge type».
- ➡ Read off the pressure gauge type.

Some pressure gauges can only be recognized as a group (e.g. ACR 261-ACR 263) and have to be set manually.

Requesting the actual pressure value

- → Select «794 : Param set» and set to «1».
- → Select «340 : Pressure».
- ➡ Read off the pressure value in mbar.

The following can be displayed, depending on the pressure gauge type:

Display (Example)	Appears when
« mbar»	no pressure gauge is connected
«<5E-4mbar»	measuring range is non-attained (depending
	on the pressure gauge in use)
«>1E3mbar»	measuring range is exceeded (depending
	on the pressure gauge in use)
«6.3E-9mbar»	valid pressure measurement range
«idfam mbar»	pressure gauge type not yet identified
«TPR250»	pressure gauge TPR 250 connected
«ACR?»	pressure gauge ACR 261, ACR 262 oder ACR
	263 connected but not yet selected (in this
	case the display «id fam» [P:340] is shown)
«Error!»	error in the pressure gauge

3.14. Backing Pump Operations

The operating modes "non-stop operations", "interval operations" or "Switch ON delayed" can be selected depending on the selected backing pump and the vacuum application. Interval operations can be selected, for example, to prolong the working life of the diaphragms in diaphragm vacuum pumps. The backing pump is switched on and off depending on the power take-up of the turbopump.



Rotary vane pumps must not be used for internal operations.

Non-stop operations backing pump

- → Select «794 : Param set» and set to «1».
- ➡ Select «025: OpMode BkP» and set to «0» for non-stop operations.

Interval operations backing pump

- → Select «794 : Param set» and set to «1».
- Select «025 : OpMode BkP» and set to «1» for interval operations.

For intermittent operations involving the backing pump, either a diaphragm pump with integrated semiconductor relay or a relay box with semiconductor relay should be used. The backing pump is switched on and off in accordance with the power take-up levels of the turbopump.

Differing power take-up levels on an idling turbopump lead to differing pressure switchpoints on various pumps. In addition, on diaphragm pumps there are differing final pressures resulting from the gas ballast equipment. This means that ideal pressure switchpoint setting via the power take-up level is not possible. Nevertheless, the advantage of intermittent operations can still be exploited by setting the pressure switch threshholds individually. In this respect operations between 5 and 10 mbar are recommended.

A vacuum meter, a DCU and a dosing valve are required in order to set the switching threshold. Instead of the vacuum meter a vacuum gauge can be connected directly to the DCU.

Setting the switching threshholds

- → Select «340 : Pressure».
- Admit air into the fore-vacuum line with the dosing valve while the pumping station is running until the fore-vacuum pressure increases to 10 mbar.
- ➡ Select «316 : TMP power».
- ➡ Read off the take-up power at 10 mbar.
- ➡ Select «711 : BKP Pon».
- Save the read-off take-up power as the upper switching threshhold.
- Proceed analogically with the lower switching threshold. Take 5 mbar as the pressure value.
- → Select «710 : BKP Poff».
- Save the read-off take-up power as the lower switching threshhold.

Switch On Delayed

- ➡ select «794 : Param set» and set to «1».
- select «025: OpMode BkP»; choose «2» for delayed switch on.

When simultaneously switching on the turbopump and the backing pump, the gas flow could cause a failure with the error message **E913** during the starting phase. In order to prevent this, it is recommended to first start the turbopump and then the backing pump or open a driven fore-vacuum valve.

In the operating mode "delayed switch on" after activation of the parameter «Pump start» **[P:010]** and «Motor TMP» **[P:023]** the turbopump is started first and as soon as a speed of 6 Hz has been exceeded the backing pump controlled via the TC is then switched on.

Should the backing pump or a fore-vacuum valve be driven by a higher level system controller, it is recommended to proceed in the same way.

3.15. Switching Off The Pumping Station

→ Depress ③ on the front panel. As an alternative, the pumping station can be switched off via the remote control, the serial interface or [P:010].

3.16. Remote Control

The following functions can be activated via the remote control (please also refer to the operating instructions for the respective turbopump):

TC 600:

Function
Venting enable "ON/OFF"
Turbopump "ON/OFF" /remote priority "ON/OFF"
Pumping Station "ON/OFF"
Heating "ON/OFF"/Error acknowledgement
Stand-by "ON/OFF"
Rotation speed setting mode via pulse width
modulation (PWM).

TC 100/TCK 100:

PIN	Function
2/d4	- Remote Priority "ON/OFF"
3/b4	- Accessory 1 "ON/OFF"
4/z4	- Accessory 2 "ON/OFF"
5/d6	- Pumping Station "ON/OFF"
6/b6	- Standby "ON/OFF" / Reset

Operating modes with the remote control

Basically there are three different possibilities with regard to the remote control with differing priorities with respect to the remote control functions:

Standard Remote Control

➡ Select «028 : OpMode rem» and set to «0».

The individual functions which can be operated with the remote control are activated via "SPS High Level". Activated individual functions cannot be operated via the serial interface nor the keyboard. Individual functions deactivated with the remote control can be operated via the serial interface or the keyboard.

Remote Control Priority

Only TC 600:



«**028 : OpMode rem**» may only be altered to «OFF» when the pump is switched off («**023 : Motor TMP**»).

Priority ON

In certain application cases as, for example, SPS control, the remote control functions can be assigned prioritized switching.

- ⇒ Select «028 : OpMode rem» and set to «1». Bridge pin 1/pin 3 on the connecting plug "remote".
- -> All set functions will be switched off excepting "motor, turbopump ON" which remains on "ON".
- -> The remote control functions can only be set via the connecting plug "remote". The DCU keyboard/serial interface is inactive.

The functions:

- Heating ON/error acknowledgment
- Stand-by ON
- Pumping station ON
- Enable venting

are activated and deactivated with the signals «1» and «0» respectively. In the rotation speed setting mode the set value standard is processed exclusively via pin 7 on the connecting plug "remote".

If pin 3 on the connection "remote" should be set to "0":

-> Values set via the remote control will be taken over except in rotation speed setting mode. Here, the set value standard is processed via the serial interface or the keyboard.

Priority OFF

- → Select «028 : OpMode rem» with f=0 Hz and set to «1».
- -> All set functions will be switched off excepting "motor, turbopump ON" which remains on "ON".
- → Set Pin3/"Remote" to «0».
- -> Operating is only possible via the DCU keyboard/serial interface (remote control not active).
- -> -Set values are not saved.
- -> In rotation speed setting mode the rotation speed set via the keyboard or serial interface will be taken over.

If «028 : OpMode rem» should be re-set to «0»:

-> Values set via the keyboard or serial interface will be taken over. Values set with «1» via the remote control will also be taken over.

Priority ON

➡ Select «028 : OpMode rem» and set to «1».

TC 100

➡ Bridge pin 2/pin 7 on the connecting plug X3.

TCK 100

- ➡ Bridge pin d4/pin z28 on the connecting plug X4.
- -> All set functions will be switched off.
- -> The remote control functions can only be set via the connecting plug X3. The DCU keyboard/serial interface is inactive.

The functions:

- Accessory 1 ON
- Accessory 2 ON
- Pumping station ON
- Standby/Reset ON

are activated and deactivated with the signals «1» and «0» respectively.

Priority OFF

- → Select «028 : OpMode rem» and set to «1».
- ➡ Remove bridge pin 2/pin 7 on the connecting plug X3.
- -> Values set via the remote control will be taken over.
- -> Operating is only possible via the DCU keyboard/serial interface (remote control not active).
- -> -Set values are not saved.

If «028 : OpMode rem» should be re-set to «0»:

-> Values set via the keyboard or serial interface will be taken over. Values set with «1» via the remote control will also be taken over.

Remote Control "Malfunction Acknowledgement"

If the reset input on the remote control is not used, it can be utilized as an external malfunction acknowledgement via the remote control; this means that after a switch off and subsequent switch on via the ""Motor TMP" or "Pumping Station" inputs, a malfunction acknowledgement will first be executed.

→ Set «028 : OpMode rem» to «2».

3.17. Venting The Turbopump

Venting is possible after the pump has been switched off. Basically, a delay time of 6 seconds is observed before each venting procedure to ensure that any possible high vacuum valve is closed. In a currentless state the venting valve is closed. Where a malfunction (error) is involved venting will proceed in accordance with the selected venting mode.

Three types of venting modes can be selected in the extended parameter set:

- ➡ Select «794 : Param set» and set to «1».
- TC 600: Allocate venting release via bridge PIN 1 and PIN 2 on the "remote" plug.
- TC 100: Allocate venting release via bridge PIN 1 and PIN 3 respectively PIN 4 (according to the output configuration).
- TCK 100: Allocate venting release via bridge z28 and b4 respectively z4 (according to the output configuration).

or

- → Call up «012 : Vent enab». Select «ON».
- ➡ Call up «030 : Vent mode». Select «0», «1» oder «2».

Venting mode «0»: automatic venting

Automatic venting means that venting begins at a specific frequency **[P:720]** after the pumping station has been switched off or a mains power failure and continues for a specific duration **[P:721]**.

In the event of a mains power failure, the set duration value cannot be guaranteed.

- ➡ Select «720 : Vent frequ».
- ➡ Set the venting frequency between «40-98%».
- ➡ Select «721 : Vent time».
- ➡ Set the venting duration in sec. between «0» and «3600».
- -> The venting valve is closed after mains power has been restored.

Venting mode «1»: venting OFF

-> The pump will not be vented.

Venting mode «2»: venting ON

-> When the pumping station is switched off, in cases of malfunction and in the event of a power failure, after a time lag of 6 seconds, venting takes place. If a high vacuum valve is installed, it can be closed in the meantime. Where a mains power failure is involved, venting will only take place as long as the pump is able to supply power to the venting valve. After power has been restored the venting valve stays open. It closes when the pumping station is switched on.

3.18. Operations Via Serial Interface RS 485

The group address of the TC 600 is 960 of the TC 100/TCK 100 is 950. All units connected to the bus must have differing serial interface addresses **[P:797]**. The connection of an RS 232 (for example, a PC) is possible via Level Converter PM 051 054-X. The description of the data communication (PFEIFFER VACUUM protocol) can be found in Operating Instructions PM 800 488 BN.

3.19. Emergency Power Operations

If during turbopump operations the power fails (warning **«F007**»), the pump rotor acts as a generator and takes over the supply of power for the electronics. In addition, a power failure is signalled by flashing green and red LEDs on the front panel (50% ON; 50% OFF). At a certain rotation speed (depending on the pump), the pump energy is no longer sufficient and communication between the DCU and the TC is interrupted and error message **«E698**» appears.

3.20. Brake Mode (only TC 600)

In order to be able to more quickly brake the pump in rotation speed setting mode, some pumps allow the connection of an external braking system (accessory on request).

Activating brake mode

➡ Call up «013 : Brake enab»; select «ON».

De-activating brake mode

→ Call up «013 : Brake enab»; select «OFF».



Malfunction «**E002**» results if the brake mode is activated and there is no connected braking system.

3.21. Configuration Of The Accessory Input/ Output (only on the TC 100 with TCS 010 or TCK 100)

The following pumping station components can be connected:

- Air cooling, venting valve, heating, backing pump.

In this respect it is necessary to configure the accessory input/output in relation to the function optionally via **[P:035]** or **[P:036]**.

➡ Select «035 : Conf. I/01».

- ➡ Select function as required:
 - 0 = air cooling (set by factory)
 - 1 = Venting valve
 - 2 = Heating
 - 3 = Backing pump

→ Select «036 : Conf. I/02».

- → Select function as required:
 - 0 = air cooling
 - 1 = Venting valve (set by factory)
 - 2 = Heating
 - 3 = Backing pump

3.22. Configuration Of The Analog Output

An analog signal (0-10 VDC) with the following information can be taken from the TC or TCK 100:

- Rotation speed of the turbopump
- Power input
- Current input.

In this respect it is necessary to configure the analog input/ output in relation to the function.

- ➡ Select «055 : Conf. A01».
- → Select function 0, 1 oder 2:
 - 0 = Rotation speed signal, 0-10 VDC = 0-100% x f_{end}
 - 1 = Power input signal , 0-10 VDC = 0-100% x p_{max}
 - 2 = Current supply signal, 0-10 VDC = 0-100% x I_{max}

Information about the values $f_{end},\,p_{max},\,l_{max}$ are readable in the operating instructions of the additional pump.

4. Error Codes

4.1. General



Errors ("Errxxx" or Error "Exxx") always lead to shut-down of the TMP, the fan, the heating and the backing pump.

 \rightarrow After the error is eliminated, depress key 2.

-> The unit is again ready to operate.

4.2. Errors During Self-Testing

The following errors can occur during self-testing performed when the DCU is switched on:

Display	Error	Possible Action
«Error E040»	Hardware error: external RAM defective	Inform PFEIFFER VACUUM-Service
«Error E042»	Hardware error: EPROM checksum	Inform PFEIFFER VACUUM-Service
«Error E043»	Hardware error: E ² PROM erratum	Inform PFEIFFER VACUUM-Service
«Error E090»	Insufficient RAM	Inform PFEIFFER VACUUM-Service
	DCU is connected to the wrong turbo electronics	Connect correct turbo electronics
«Error E698»	The connected drive unit does not respond	Check communication lead between TC and DCU, switch on TC

4.3. Errors During Operations

During operations, errors and warnings which occur are, independent of the function of the service line, always shown in the LC display and can be additionally requested in parameter **[P:303]** «Error code». In addition, parameters 360 to 369 retain the last ten errors or warnings which occurred. After an error has occurred all parameters can be viewed but no longer altered. Exception: Error **[E698]** «TC does not respond». Here, no actualisation of the parameter is possible until the communication has been restored.

AP excess rotation speed wer pack unit error art-up time error hen the start-up phase is completed, the ro- tion speed of the pump drops below the rota- n speed switchpoint. werating fluid deficiency <u>nnection TC and pump</u> e heating type identified in the self test has	At B- S/B S/B S/B S/B	 Inform PFEIFFER VACUUM Service. If operations with mains voltage 90 - 132 VAC, check settings [P:029] (see chapter 3.4) Check power pack output voltage. Check settings [P:013] (see chapter 3.20). Inform PFEIFFER VACUUM Service. Set correct start-up time. Open vacuum valve. Reduce fore-vacuum pressure. Eliminate leak. Check free running of the turbo pump. Check oil level. Request status of the oil sensor via [P:301].
art-up time error hen the start-up phase is completed, the ro- ion speed of the pump drops below the rota- n speed switchpoint. perating fluid deficiency	S/B S/B	 Check power pack output voltage. Check settings [P:013] (see chapter 3.20). Inform PFEIFFER VACUUM Service. Set correct start-up time. Open vacuum valve. Reduce fore-vacuum pressure. Eliminate leak. Check free running of the turbo pump. Check oil level. Request status of the oil sensor via [P:301].
hen the start-up phase is completed, the ro- ion speed of the pump drops below the rota- n speed switchpoint. herating fluid deficiency nnection TC and pump	S/B	 Open vacuum valve. Reduce fore-vacuum pressure. Eliminate leak. <u>Check free running of the turbo pump.</u> Check oil level. Request status of the oil sensor via [P:301].
nnection TC and pump		 Check oil level. Request status of the oil sensor via [P:301].
nnection TC and pump e beating type identified in the self test bas	S/B	- Inform PFEIFFER VACUUM Service.
e heating type identified in the self test has	0/0	- Check connection TC and pump.
en changed by pulling the plug or by an ror.	В	Change configuration of heating or cooling unit. Inform PFEIFFER VACUUM Service.
ror in the TC controller	S/B	Reset the controller with mains 0N/0FF with the pump at standstill (f=0 Hz). Possibly Inform PFEIFFER VACUUM Service.
correct pump identification resistance	S	- Inform PFEIFFER VACUUM Service.
ror in the temperature monitoring TC	S/B	 Reset the controller with mains ON/OFF with the pump at standstill (f=0 Hz). Possibly Inform PFEIFFER VACUUM Service.
ror of the temperatur sensor inside the TC	S/B	 Reset the controller with mains ON/OFF with the pump at standstill (f=0 Hz). Possibly Inform PFEIFFER VACUUM Service.
ror in the motor stages or control	S/B	- Possibly Inform PFEIFFER VACUUM Service.
does not respond	S/B	 Check connection DCU - TC. Change the DCU. Possibly Inform PFEIFFER VACUUM Service.
	S	 Error resets itself 5 times. Then switching off via «E006» Possibly set the op. mode backing pump [P:025] up to "2" Check the free rotation of the pump.
		does not respond S/B

1) only TC 600/TC750

²⁾ This error message is not displayed via switch output 2 (collective error message);

 $^{(3)}$ Error acknowledgement of this failure is only possible for 5 times. S: self test; B: operations

4.4. Warnings

Warnings ("Wrnxxx" or "Warning Fxxx") are only displayed and (otherwise than is the case with errors) do not cause components to be shut down.

Code	Description	Explanations
F001 ¹⁾	TMS heating start-up time elapsed	TMS heating start-up time elapsed.
F002 ¹⁾	TMS limit temperature	TMP-temperature > 100°C.
F003 ¹⁾	TMS-heating circuit temperature sensor	TMP temperature not within the range 5°C and 120°C.
F007	Mains power failure	Operations voltage has failed.
F039 ¹⁾	Protective conductor warning TC	Potential of the supply voltage in contact with the protective conductor PE
F110 ²⁾	Pressure gauge defective	Pressure gauge disconnected during operations
¹⁾ only TC 600/750 ²⁾ Warning only in DCU.		



Warning «**F039**» must be eliminated without delay otherwise there is a danger of an electric shock.

5. Supplementary Information

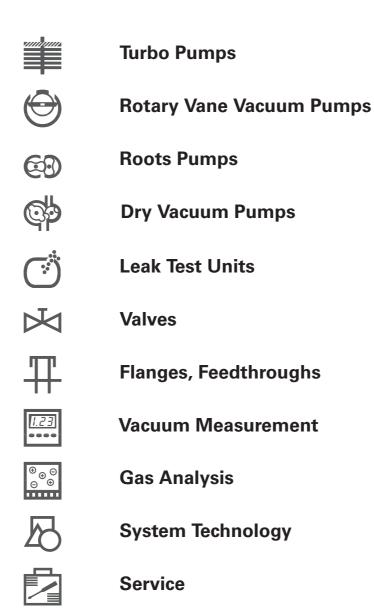
Information with regard to:

- Product
- Proper Use
- Installation
- Operation
- Errors
- Maintenance and Service
- Technical Data

can be found in Operating Instructions PM 800 477 BE for "Display And Operating Unit DCU" which is included in this consignment.

The PFEIFFER VACUUM protocol for Serial Interface RS 485 is described in Operating Instructions PM 800 488 BE which is included in this consignment.

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